

Statistical and computation aspects of shape-constrained inference for autocovariance sequence estimation¹

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Introduction: MCMC for Bayesian statistics

- ▶ probability measure π on (X, \mathcal{X}) , e.g., Bayesian posterior distribution
- ▶ want $\mu = \int g(x) \pi(dx) = E_\pi[g]$
- ▶ construct Markov chain X_0, X_1, \dots with stationary distribution π
- ▶ estimate μ by

$$\hat{\mu}_M = M^{-1} \sum_{t=0}^{M-1} g(X_t)$$

- ▶ quantify uncertainty in $\hat{\mu}_M$
- ▶ turns out, this problem is closely related to estimating the autocovariance function $\gamma : \mathbb{Z} \rightarrow \mathbb{R}$, defined as

$$\gamma(k) = \text{Cov}_\pi(g(X_0), g(X_k)), \quad k \in \mathbb{Z},$$

Asymptotic variance

Suppose X_0, X_1, \dots are a Markov chain sequence with a stationary probability measure π and transition kernel Q

- ▶ The **asymptotic variance** $\sigma^2 = \sum_{k=-\infty}^{\infty} \gamma(k)$ aggregates the covariance from all lags. Given an estimate $\hat{\gamma}$ of γ , we may consider $\hat{\sigma}^2 = \sum_{k=-\infty}^{\infty} \hat{\gamma}(k)$.
- ▶ $\text{Var}(\hat{\mu}_M) \approx \sigma^2/M$ for large M .
 - ▶ σ^2 is the CLT variance, or the limit of $M\text{Var}(\hat{\mu}_M)$ as $M \rightarrow \infty$ [e.g. Haggstrom and Rosenthal, 2007]

Sample autocovariances

- ▶ For a given sample X_0, X_1, \dots, X_{M-1} of size M , the empirical autocovariance sequence $r_M : \mathbb{Z} \rightarrow \mathbb{R}$ defined as

$$r_M(k) = \begin{cases} \frac{1}{M} \sum_{t=0}^{M-k-1} \tilde{g}(X_t) \tilde{g}(X_{t+k}) & , |k| \leq M - 1 \\ 0 & , |k| \geq M \end{cases}$$

is a natural estimator for γ , where $\tilde{g}(X_t) = g(X_t) - \frac{1}{M} \sum_{t=0}^{M-1} g(X_t)$.

- ▶ while $r_M(k) \rightarrow \gamma(k)$ for each k , r_M is rather terrible as an estimator for γ .
 - ▶ For example, summing the empirical autocovariances $\hat{\sigma}_{Emp}^2 = \sum_{k=-\infty}^{\infty} r_M(k)$ leads to an **inconsistent** estimator of σ^2 .
 - ▶ variance of $r_M(k)$ is “too large” compared to the signal $\gamma(k)$ for large k .

Spectral density

For a sequence $f : \mathbb{Z} \rightarrow \mathbb{R}$, define the discrete-time Fourier transform of f : $\hat{f} : [-\pi, \pi] \rightarrow \mathbb{R}$ such that

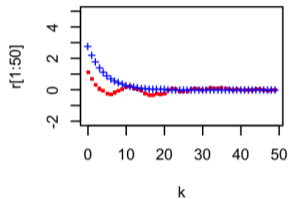
$$\hat{f}(\omega) = \sum_{k \in \mathbb{Z}} f(k) e^{-i\omega k}$$

- ▶ (spectral density) $\phi_\gamma(\omega) = \sum_{k \in \mathbb{Z}} \gamma(k) e^{-i\omega k}$
- ▶ (periodogram) $\hat{r}_M(\omega) = \sum_{k \in \mathbb{Z}} r_M(k) e^{-i\omega k}$, which is an estimate of ϕ_γ
- ▶ By Parseval's identity, $\sum_{k \in \mathbb{Z}} (\gamma(k) - r_M(k))^2 = \frac{1}{2\pi} \int_{[-\pi, \pi]} (\phi_\gamma(\omega) - \hat{r}_M(\omega))^2 d\omega$
 - ▶ l_2 square distance between r_M and γ = integrated square error between $\tilde{\phi}_M$ and ϕ_γ
- ▶ $\sigma^2 = \phi_\gamma(0)$

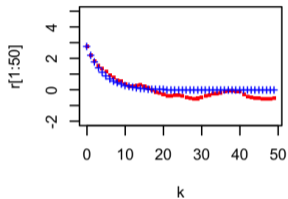
Red = Empirical autocovariance (periodogram)

Blue = True autocovariance (spectral density)

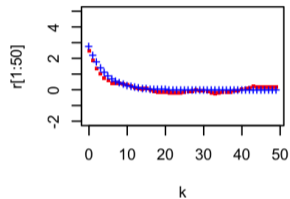
Autocovariances, M=50



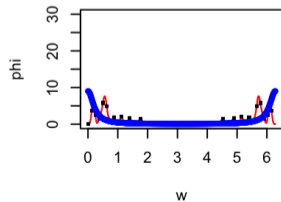
Autocovariances, M=200



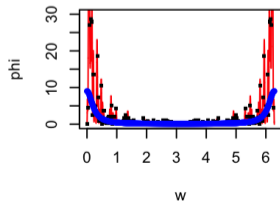
Autocovariances, M=800



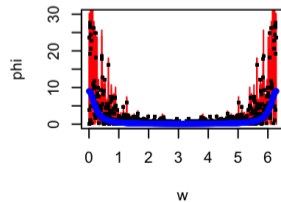
Spectral Density



Spectral Density



Spectral Density



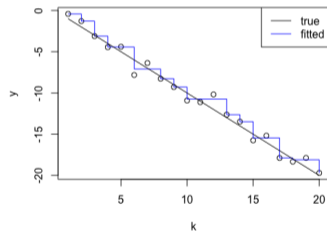
Estimation with shape constraints

Estimation with various shape constraints can be of interest:

► Monotonicity

- Isotonic regression [e.g., Barlow et al. [1972]]:
for finite $y \in \mathbb{R}^n$, $y_k = f_k + \epsilon_k$, $f_k \geq f_{k+1}$ for
 $k = 1, \dots, n$.

$$\hat{f}_{iso} = \arg \min_{f; f_k \geq f_{k+1}, k=1, \dots, d-1} \|y - f\|^2$$



Estimation with shape constraints

- ▶ Monotonicity (cont'd)
 - ▶ Estimation of a discrete **monotone** pmf [Jankowski and Wellner, 2009]

$$\hat{p}_M(k+1) \geq \hat{p}_M(k) \geq 0, \text{ for } n, k \in \mathbb{N}$$

- ▶ Estimation of a discrete **completely monotone** pmf [Balabdaoui and de Fournas-Labrosse, 2020]

$$(-1)^n \Delta^n \hat{p}(k) \geq 0, \text{ for } n \in \mathbb{N}$$

where $\Delta^0 p(k) = p(k)$, $\Delta^n p(k) = \Delta^{n-1} p(k+1) - \Delta^{n-1} p(k)$, for $n = 1, 2, 3, \dots$, $k \in \mathbb{N}$

- ▶ Convexity, Log-concavity, etc. [e.g., Dümbgen and Rufibach [2011], Balabdaoui and Durot [2015], Kuchibhotla et al. [2017]]
- ▶ initial sequence estimators of Geyer [1992]

Mixture representations

Commonly, shape constraints on a function are related to a mixture representation for the function

- ▶ Complete monotonicity of sequence m (positive, decreasing, convex, ...):

$$(-1)^n \Delta^n m(k) \geq 0, \forall n, k \in \mathbb{N} \quad \iff$$

$$\exists \mu \text{ s.t. } m(k) = \int_{[0,1]} x^k \mu(dx), \forall k \in \mathbb{N}$$

[Hausdorff moment theorem Hausdorff, 1921]

- ▶ convex sequence: mixture of “trifunctions” [Durot et al., 2013]
- ▶ k -monotone: mixture of Beta(1, k) densities [Balabdaoui and Wellner, 2005]
- ▶ (Spatial statistics) Matérn covariance: mixture of Gaussians

Shape constraints in autocovariance function γ

- ▶ It is a well known result that the true autocovariance sequence γ for a reversible Markov chain admits the following representation [Rudin, 1973]:

$$\gamma(k) = \int x^{|k|} F(dx) \quad (1)$$

for a positive measure F supported on $[-1, 1]$

- ▶ Moreover, if a chain has a positive spectral gap, then F is supported on $[-1 + \delta_\gamma, 1 - \delta_\gamma]$ for some $\delta_\gamma > 0$ (true for e.g., an IID sample or a reversible chain with geometric ergodicity [Roberts and Rosenthal, 1997]).
- ▶ γ is a $[-1 + \delta_\gamma, 1 - \delta_\gamma]$ moment sequence for a reversible and geometrically ergodic chain.

Our approach 1: L2 projection of empirical autocovariance sequence

Let $\mathcal{M}_\infty(\delta)$ denote the set of $[-1 + \delta, 1 - \delta]$ moment sequences

(Un-weighted) Moment LSE [Berg and Song, 2023]:

$$\Pi(r_M; \delta) = \arg \min_{m \in \mathcal{M}_\infty(\delta) \cap \ell_2(\mathbb{Z})} \sum_{k \in \mathbb{Z}} \{r_M(k) - m(k)\}^2 \quad (2)$$

- ▶ projection onto the ℓ_2 moment sequence set
- ▶ here δ is a hyperparameter
- ▶ ignores unequal variances and non-zero covariances in $\{r_M(k)\}_{k \in \mathbb{Z}}$

Our approach 2: Weighted inner-product norm projection

- ▶ previously: covariance fitting objective $\|r_M - m\|_2^2 = \sum_{k=-\infty}^{\infty} (r_M(k) - m(k))^2$
- ▶ what about a weighted squared error loss function?
 - ▶ In regression, $Y = X\beta + \epsilon$, $Var(Y) = \Sigma$
 - ▶ $\hat{\beta}_{OLS} = \operatorname{argmin}_{\beta} \sum_{k=1}^n (Y_k - x_k^T \beta)^2 = (Y - X\beta)^T (Y - X\beta)$
 - ▶ $\hat{\beta}_{GLS} = \operatorname{argmin}_{\beta} (Y - X\beta)^T \Sigma^{-1} (Y - X\beta)$
- ▶ covariances of r_M not easy to work with
 - ▶ $\operatorname{Cov}(r_M(j), r_M(k)) \neq 0$ for all j, k such that $|j|, |k| < M \rightarrow$ covariance matrix **not sparse**

Our approach 2: Weighted inner-product norm projection

- ▶ recall the Parseval's identity:

$$\sum_{k \in \mathbb{Z}} (r_M(k) - m(k))^2 = \frac{1}{2\pi} \int_{[-\pi, \pi]} (\hat{r}_M(\omega) - \hat{m}(\omega))^2 d\omega$$

- ▶ Periodogram at Fourier frequencies:

$$\hat{r}_M(\omega_k) \stackrel{ind}{\approx} \phi(\omega_k) \text{Exp}(1) \quad k = 0, \dots, \lfloor M/2 \rfloor.$$

$\omega_k = 2\pi k/M$, $k = 0, \dots, M - 1$ [e.g., Brockwell and Davis, 1991, Kokoszka and Mikosch, 2000]

Our approach 2: Weighted inner-product norm projection

Given a good estimate $\phi_M(\omega)$ of true spectral density, define
Weighted Moment LSE [Song and Berg, 2024+]

$$\Pi^{\phi_M}(r_M; \delta) = \arg \min_{f \in \mathcal{M}_\infty(\delta) \cap \ell_2(\mathbb{Z}, \mathbb{R})} \|r_M - f\|_{\phi_M}^2$$

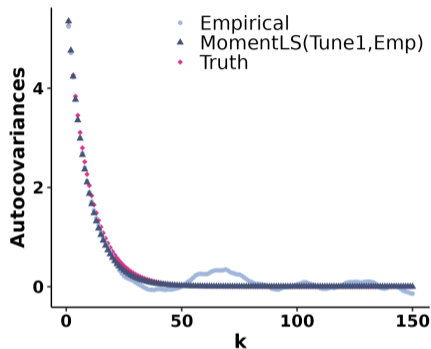
where the weighted inner-product norm $\|\cdot\|_{\phi_M}$ is defined as

$$\|r_M - f\|_{\phi_M}^2 = (2\pi)^{-1} \int_{[-\pi, \pi]} \frac{\{\hat{r}_M(\omega) - \hat{f}(\omega)\}^2}{\phi_M(\omega)^2} d\omega$$

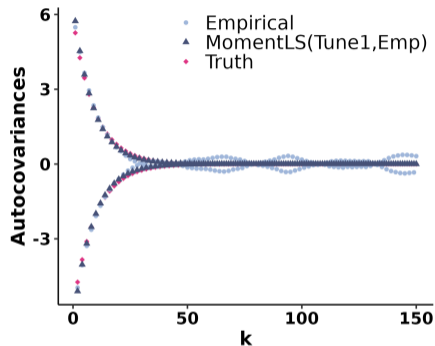
and \hat{r}_M and \hat{f} are Fourier transform of r_M and f .

- ▶ another interpretation of the objective: estimate spectral density using **shape-constraints on Fourier coefficients**

Moment LSE in practice



(a) $\rho = 0.9$



(b) $\rho = -0.9$

Figure: For an AR(1) chain with (a) $\rho = 0.9$ and (b) $\rho = -0.9$, a comparison of true, empirical, and moment LS estimated autocovariances from a single simulation with $M = 8000$.

Estimator

$$\Pi^{\phi_M}(r_M; \delta) = \arg \min_{f \in \mathcal{M}_\infty(\delta) \cap \ell_2(\mathbb{Z}, \mathbb{R})} \|r_M - f\|_{\phi_M}^2$$

Objective: minimize $\|r_M - f\|_{\phi_M}^2$ over valid autocovariances f

- ▶ ie sequences satisfying

$$f(k) = \int_{[-1+\delta, 1-\delta]} \alpha^{|k|} \mu(d\alpha), \quad \forall k \in \mathbb{Z}$$

for a positive measure μ with $\text{Supp}(\mu) \subseteq [-1 + \delta, 1 - \delta]$.

- ▶ $0 < \delta \leq 1$ is a tuning parameter (estimated from data)

Finite, discrete support of estimated mixing measure

Proposition (ref Song and Berg [2024+])

- ▶ Let $C = [-1 + \delta, 1 - \delta]$
- ▶ Suppose $r(k) = r(-k)$, $\forall k$, and $r(k) = 0$ for $|k| > M_0 \geq 0$
- ▶ μ_C^ϕ denote the representing measure for $\Pi^\phi(r; C)$

Then $|\text{Supp}(\mu_C^\phi)| \leq \frac{n}{2} + 1$, where n is the smallest even number s.t. $n > M_0$.

- ▶ The mixing measure μ_C^ϕ for $\Pi^\phi(r; C)$ is finite and discrete, with at most $\approx M/2$ support points, where M is the MCMC sample size
- ▶ proof uses techniques from total positivity [e.g. Karlin, 1968] to bound number of support points
- ▶ in practice much smaller than $M/2$

Computation

- ▶ The objective is:

$$\|r_M - f\|_{\phi_M}^2 = \text{const} + \frac{1}{2\pi} \left\{ \int_{[-\pi, \pi]} -2 \frac{\hat{r}_M(\omega) \hat{f}(\omega)}{\phi_M(\omega)^2} d\omega + \int_{[-\pi, \pi]} \frac{\hat{f}(\omega)^2}{\phi_M(\omega)^2} d\omega \right\}$$

- ▶ approximate $\Pi^{\phi_M}(r_M; \delta)$ with $\Pi^{\phi_M}(r_M; C)$ where $C = \{\beta_1, \dots, \beta_s\} \subset [-1 + \delta, 1 - \delta]$
- ▶ optimize over f with representing measures μ of form

$$\mu = \sum_{i=1}^s c_i \delta_{\beta_i}$$

Computation

For f with representing measure $\mu = \sum_{i=1}^s c_i \delta_{\beta_i}$

$$\|r_m - f\|_{\phi_M}^2 = \text{const} - 2 \sum_{i=1}^s c_i a_i + \sum_{i=1}^s \sum_{j=1}^s c_i c_j B_{ij}$$

where

$$B_{ij} = \langle x_{\beta_i}, x_{\beta_j} \rangle_{\phi_M} = \frac{1}{2\pi} \int_{[-\pi, \pi]} \frac{K(\beta_i, \omega) K(\beta_j, \omega)}{\phi_M(\omega)^2} d\omega$$

$$a_i = \langle x_{\beta_i}, r_M \rangle_{\phi_M} = \frac{1}{2\pi} \int_{[-\pi, \pi]} \frac{\hat{r}_M(\omega) K(\beta_i, \omega)}{\phi_M(\omega)^2} d\omega$$

$$K(\beta, \omega) = \frac{1 - \beta^2}{1 - 2\beta \cos(\omega) + \beta^2} \quad (\text{Poisson kernel})$$

- B_{ij}, a_i are computable from data. This is a quadratic programming problem with non-negativity constraints on c_i .

Plug-in spectral density and asymptotic variance estimators

For a **weighted momentLS estimator** $\Pi^{\phi_M}(r_M; \delta)$, we consider

$$\phi_{\delta M}^W(\omega) = \sum_{k \in \mathbb{Z}} \Pi^{\phi_M}(r_M; \delta)(k) e^{-i\omega k} \quad (\text{spectral density})$$

$$\sigma_{\delta M, W}^2 = \sum_{k \in \mathbb{Z}} \Pi^{\phi_M}(r_M; \delta)(k) \quad (\text{asymptotic variance})$$

Statistical guarantee

Theorem ([Song and Berg, 2024+])

Consider a Harris ergodic, π -reversible, and geometrically ergodic Markov chain X_0, X_1, \dots . Suppose a weight function ϕ_M is a twice continuously differentiable, positive function with bounded derivatives and does not vanish asymptotically. Let μ_γ denote the representing measure for γ . Suppose $\delta > 0$ is chosen so that $\text{Supp}(\mu_\gamma) \subseteq [-1 + \delta, 1 - \delta]$. Then

1. (ℓ_1 -consistency) $\|\gamma - \Pi^{\phi_M}(r_M; \delta)\|_1 \rightarrow 0, P_x$ -a.s.
2. (spectral density) $\sup_{\omega \in [-\pi, \pi]} |\phi_{\delta M}^W(\omega) - \phi_\gamma(\omega)| \rightarrow 0 P_x$ -a.s.
3. (asymptotic variance) $\sigma_{\delta M, W}^2 \rightarrow \sigma^2(\gamma) P_x$ -a.s.

for each initial condition $x \in \mathcal{X}$, where we define $\sigma^2(\gamma) = \sum_{k \in \mathbb{Z}} \gamma(k)$

- ▶ spectral density estimate $\phi_{\delta M}$ from the unweighted momentLS satisfies the regularity conditions

Empirical performance (asymptotic variance)

Bayesian LASSO example [Rajaratnam et al., 2019]

Table: *Estimated average mean squared error (s.e.) for the asymptotic variance estimators*

(a) Asymptotic variance mean squared error¹

	Bartlett	OBM	Init-con	IO-kernel	mLS_uw	mLS_w
β_0	333.45 (14.90)	343.99 (15.19)	162.57 (10.41)	164.04 (9.82)	163.10 (10.78)	153.18 (10.37)
β_1	291.61 (13.49)	300.97 (13.75)	166.04 (11.06)	160.04 (9.99)	164.35 (11.04)	148.67 (10.02)
β_2	368.42 (18.31)	383.17 (18.83)	227.44 (15.42)	230.95 (14.68)	229.72 (16.54)	214.63 (15.28)
β_3	98.26 (4.89)	101.43 (5.01)	55.91 (3.46)	58.10 (3.32)	52.96 (3.27)	49.24 (3.14)
β_4	63.69 (3.57)	65.62 (3.64)	41.21 (2.66)	37.00 (2.32)	38.75 (2.59)	35.53 (2.39)
β_5	19.65 (1.00)	20.10 (1.01)	11.89 (0.84)	12.27 (0.81)	12.06 (0.89)	11.62 (0.84)
β_6	141.89 (6.94)	147.49 (7.17)	87.85 (5.50)	82.63 (4.68)	86.93 (5.54)	81.21 (5.27)
β_7	0.54 (0.03)	0.55 (0.03)	0.71 (0.05)	0.53 (0.03)	0.49 (0.03)	0.45 (0.03)
σ^2	351.56 (18.28)	357.09 (18.47)	474.50 (32.61)	490.00 (17.44)	337.27 (23.94)	311.73 (21.89)

¹ values for β_0 - β_7 are scaled by 10^4 , and σ^2 is scaled by 10^2

Empirical performance (spectral density)

$$\text{Integrated squared error} = (2\pi)^{-1} \int_{[-\pi, \pi]} \{\hat{\phi}(\omega) - \phi(\omega)\}^2 d\omega$$

(a) spectral density mean integrated squared error²

	Bartlett	IO-kernel	mLS_uw	mLS_w
β_0	177.58 (6.11)	101.31 (3.95)	80.85 (3.64)	74.76 (3.45)
β_1	153.17 (5.42)	92.70 (3.70)	75.28 (3.49)	68.34 (3.29)
β_2	198.89 (6.98)	128.41 (5.34)	103.72 (5.01)	94.98 (4.75)
β_3	76.46 (2.53)	50.57 (1.85)	37.32 (1.66)	34.89 (1.63)
β_4	61.09 (1.97)	37.88 (1.46)	29.41 (1.34)	27.04 (1.27)
β_5	12.52 (0.50)	9.07 (0.40)	7.37 (0.38)	7.10 (0.37)
β_6	73.69 (2.69)	48.30 (1.85)	40.49 (1.81)	37.58 (1.77)
β_7	2.17 (0.06)	2.17 (0.04)	1.31 (0.05)	1.27 (0.05)
σ^2	113.55 (3.49)	168.96 (2.39)	84.01 (2.99)	82.44 (2.91)

² values for β_0 - β_7 are scaled by 10^5 , and σ^2 is scaled by 10^2

Summary

- ▶ We propose novel shape-constrained estimators for the autocovariance sequence and weighing framework resulting from a reversible Markov chain.
 - ▶ exploits the representability of the autocovariances of reversible Markov chains as the moments of a unique positive measure supported on $[-1, 1]$.
 - ▶ leverages asymptotic independence in the Fourier transform of the periodogram
- ▶ We provide a theoretical analysis of the proposed estimators, in particular, we proved
 - ▶ a.s. ℓ_2 consistency of the momentLSE sequence,
 - ▶ a.s. consistency of the asymptotic variance estimator based on the momentLSE sequence for the true asymptotic variance σ^2 .
- ▶ We show our asymptotic variance estimators empirically outperform other state-of-the art estimators.

This talk is based on the following two papers:

- ▶ Berg S and Song H, Efficient shape-constrained inference for the autocovariance sequence from a reversible Markov chain, *Annals of Statistics*, 2023
- ▶ Song H and Berg S, Weighted shape-constrained estimation for autocovariance sequence from a reversible Markov chain, 2024+, on ArXiv soon

Thank you!

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Choice of δ

Our theoretical results cover the case of fixed tuning parameter δ satisfying $0 < \delta \leq \Delta(F)$

Empirically,

- ▶ ℓ_2 norm convergence seems to hold even with $\delta = 0$
- ▶ But convergence of the estimated asymptotic variance is lost with $\delta = 0$

In Berg and Song [2023] we suggest a rule for tuning δ , based on a modification of a batch-size estimation procedure from Politis [2003].

Under the assumption

$$\max_{k=0, \dots, M-1} |\hat{\rho}_M(k) - \rho(k)| = O_P(\sqrt{\log M/M}) \quad (3)$$

on the sample autocorrelations, we show our rule leads to a conservative (not too large) choice of δ .

Empirical Studies

1. Empirical illustration of the convergence properties of Moment LSEs

- ▶ Recall that the Moment LSE resulting from an input sequence r_M is the projection $\Pi_\delta(r_M)$ of r_M onto the set $\mathcal{M}_\infty([-1 + \delta, 1 - \delta]) \cap \ell_2(\mathbb{Z})$.
- ▶ We proved the **a.s. convergence of the autocovariance sequence** (in L2 sense) and **a.s. convergence of the asymptotic variance estimate** of the moment LS estimators $\Pi_\delta(r_M)$ for any choice of $\delta > 0$ such that $\delta > 0$ and $\text{Supp}(F) \subseteq [-1 + \delta, 1 - \delta]$.
- ▶ We empirically explore convergence of both the autocovariance sequence and the asymptotic variance estimators at varying δ levels, including cases in which the support of F is not contained in $[-1 + \delta, 1 - \delta]$.

A few extra slides: Empirical Studies

Empirical illustration of the convergence properties of Moment LSEs

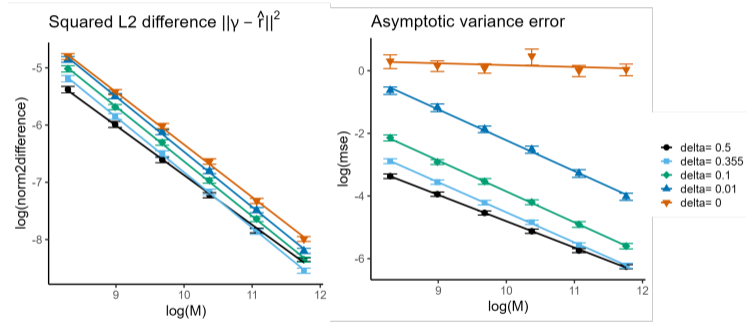


Figure: *Metropolis-Hastings example*. The support of the representing measure for γ is contained in $[-.645, .645]$, i.e., the valid δ range is $0 < \delta \leq .355$.

A few extra slides: Empirical Studies

Empirical illustration of the convergence properties of Moment LSEs

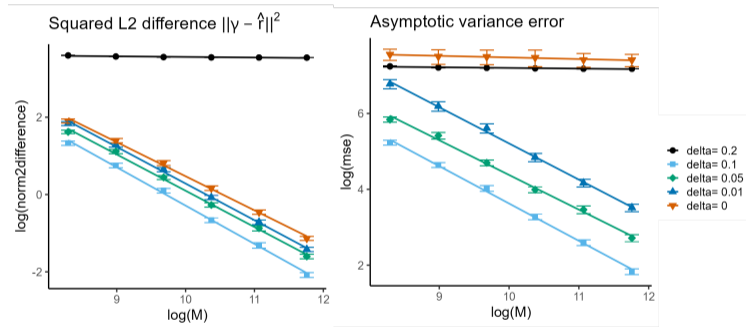


Figure: $AR(1)$ example with $\rho = .9$. The representing measure has a single support point at $.9$. The valid δ range is $0 < \delta \leq .1$.

A few extra slides: Empirical Studies

Comparison with other state-of-the-art estimators

For the Bartlett windowed estimators, BM, OBM, and Moment LSEs, hyperparameters are required. We used oracle hyperparameter settings:

- ▶ From Flegal and Jones [2010], for the BM and OLBM methods, the mean-squared-error optimal batch sizes for estimating $\sigma^2(\gamma)$ are

$$b_M^{(\text{BM})} = \left(\frac{\Gamma^2 M}{\sigma^2(\gamma)} \right)^{1/3} = C_2 M^{1/3} \quad \text{and} \quad b_M^{(\text{OLBM})} = \left(\frac{8\Gamma^2 M}{3\sigma^2(\gamma)} \right)^{1/3} = C_3 M^{1/3}$$

respectively, where $\Gamma = -2 \sum_{s=1}^{\infty} s\gamma(s)$. Since the spectral variance estimator based on the Bartlett window is asymptotically equivalent to OLBM [Damerджи, 1991], we let $C_1 = C_3$.

- ▶ For the choice of oracle δ , we let $\delta = 1 - \sup |\text{Supp}(F)|$